

Compressing exterior Helmholtz problems: 2D indefinite Laplacian

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October 2016

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1 Introduction

This script reproduces Example 6.2 in [2]. It computes RKFIT approximants for $f_h(A)\mathbf{b}$, where A is an indefinite matrix corresponding to the discretization of a 2D Laplacian on a square domain with Neumann boundary conditions; hence DCT2 can be used to diagonalize this matrix. The function to be approximated is $f_h(\lambda) = \sqrt{\lambda + (h\lambda/2)^2}$. The RKFIT approximants are compared to the uniform two-interval Zolotarev approximants in [1].

2 The code

```
n = 150; N = n^2;
h = 1/n; % grid step (now including boundary points for Neumann
          bcs)
k = 15;
L = gallery('tridiag',n); L(1,1) = 1; L(n,n) = 1;
L2 = kron(speye(n),L) + kron(L,speye(n));
eeL = 2-2*cos(pi*(0:n-1)/n).'; % evs of L
[ee1,ee2] = meshgrid(eeL);
eeL2 = (ee1(:)+ee2(:)); % evs of L2 ordered for DCT
% fL2v computes f(L2)*v using 2d DCT
fL2v = @(f,v) reshape(idct2(reshape(f(eeL2) .* ...
    reshape(dct2(reshape(v,n,n)),N,1),n,n)),N,1);
```

```

fL2V = @(f,V) util_colfun(@(v) fL2v(f,v),V);

% matrix A and matrix-vector product AV
A = 1/h^2*L2 - k^2*speye(N);
AV = @(V) fL2V(@(z) z/h^2-k^2,V);

% handles for rkfit
AB.solve = @(nu, mu, x) fL2v(@(z) 1./(nu*(z/h^2-k^2)-mu),x);
AB.multiply = @(rho, eta, x) fL2v(@(z) rho*(z/h^2-k^2)-eta,x);

% multiply with f(A)
fAV = @(f,V) fL2V(@(z) f(z/h^2-k^2),V);

% multiply with analytic DtN map
ee = sort(eeL2/h^2 - k^2).'; %ee = sort(eig(full(A)))
.F;
%F = sqrtm(full(A) + (h*full(A)/2)^2);
FV = @(V) fAV(@(z) sqrt(z+(h*z/2).^2),V);

bt = randn(N,1); bt = bt/norm(bt); % training vector
b = randn(N,1); b = b/norm(b);

a1 = min(ee);
b1 = max(ee(ee<0));
a2 = min(ee(ee>0));
b2 = max(ee);

```

Initialize RKFIT parameters.

```

param = struct;
param.reduction = 0;
param.k = 1; % superdiagonal
param.tol = 0;
param.real = 0;

for m = 1:20, % in the paper [2] this is 25

    % run rkfit with training vector
    param.maxit = 10;
    xi = inf*ones(1,m-1); % take m-1 initial poles
    [xi, ratfun, misfit, out] = rkfit(FV, AB, bt, xi, param);
    if m==1, err_rkfitt = out.misfit_initial; iter_rkfit = 0;
    else
        [err_rkfitt(m), iter_rkfit(m)] = min(misfit);
        iter_rkfit(m) = find(misfit <= 1.01*min(misfit),1);
    end

    % recompute best ratfun and compute error for vector b
    param.maxit = iter_rkfit(m);
    xi = inf*ones(1,m-1); % take m-1 initial poles
    [xi, ratfun, misfit, out] = rkfit(FV, AB, bt, xi, param);
    err_rkfit(m) = norm(FV(b) - fAV(ratfun,b))/norm(FV(b));

```

```

ex = @(x) sqrt(x + (h*x/2).^2);
zolo = rkfun('sqrt2h',a1,b1,a2,b2,m,h);
err_zolo(m) = norm(FV(b) - fAV(@(z) zolo(z),b))/norm(FV(b));

if m == 10, % some plots for m = 10
    figure
    semilogy(NaN); hold on
    lint = util_log2lin([b1,a2],[a1,b1,a2,b2],.1);
    fill([lint(1:2),lint([2,1])], [1e-25,1e-25,1e15,1e15],
        ...
        .85*[1,1,1], 'LineStyle', '-')
    ylim([1e-8,10])
    ax = [ -10.^{5:-1:2} , 0 , 10.^{2:5} ];
    linax = util_log2lin(ax,[a1,b1,a2,b2],.1);
    %labels = num2str(ax(:),'%1.0G');
    set(gca,'XTick',linax,'XTickLabel',ax)

    xx = [ -logspace(log10(-a1),log10(-b1),1000) , linspace(
        b1,a2,200) , ...
        logspace(log10(a2),log10(b2),1000) ];
    xx = union(xx,ee);
    xxt = util_log2lin(xx,[a1,b1,a2,b2],.1);
    eet = util_log2lin(ee,[a1,b1,a2,b2],.1);
    hdl1 = semilogy(xxt,abs(ratfun(xx) - ex(xx)), 'r-');
    semilogy(eet,abs(ratfun(ee) - ex(ee)), 'r+')
    hdl2 = semilogy(xxt,abs(zolo(xx) - ex(xx)), 'b--');
    legend([hdl1,hdl2],'RKFIT','Zolotarev ')
    xlim([0,1])
    title(['Error Curves, n = ' num2str(m)])
    grid on
    set(gca,'layer','top')

    % plot residues
    figure
    [resid,xi] = residue(mp(ratfun),2);
    resid = double(resid); xi = double(xi);
    semilogy(xi,'rx')
    axis([-6.2e4,1.2e4,-5e3,-5]), hold on
    labels = num2str(abs(resid),'%0.1g');
    hdl = text(real(xi)+1e3, imag(xi)*1.1, labels);
    set(hdl,'Color','r','FontSize',16,'Rotation',0)
    set(hdl(end),'Rotation',0)
    title(['Poles and Abs(Residues), n = ' num2str(m)])
    grid on

    % plot grid steps
    figure
    [grid1,grid2,absterm,cnd,pf,Q] = contfrac(mp(ratfun));
    grid1 = double(grid1); grid2 = double(grid2);
    loglog(grid1,'ro'), hold on

```

```

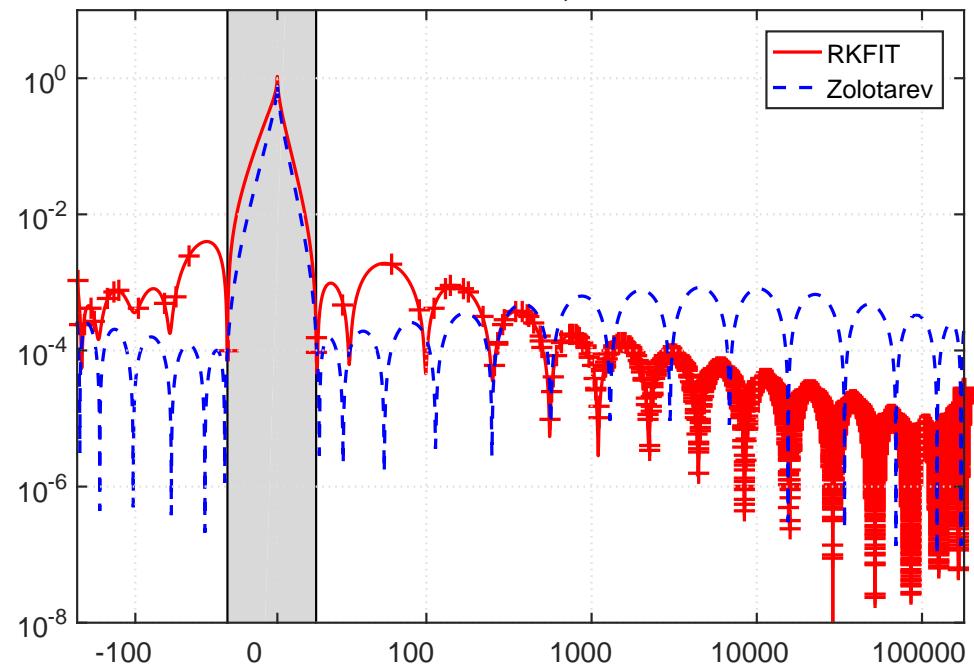
loglog(grid2, 'r*')
legend('Primal','Dual','Location','SouthWest')
title(['Grid Steps, n = ' num2str(m)])
grid on, axis([2e-3,5e-1,-1,-1e-8])

% plot solution slices
figure
U = out.V*double(Q); % first col = F*b, then U0,U1,etc.
U(:,2) = b; % get rid of tiny imaginary parts if b is
    real
Vol = []; % build volume object
for j = 2:size(U,2),
    Vol(:,j-1,:) = reshape(U(:,j),n,n);
end
neps = min(min(min(abs(Vol))))/1;
Vol(:,j,:)=zeros(n,n)+neps;
[x,y,z] = meshgrid(0:1:j-1,linspace(0,1,n),linspace(0,1,
    n));
xslice = 0:1:j-1; yslice = []; zslice = [];
hdl = slice(x,y,z,log10(abs(Vol)),xslice,yslice,zslice);
set(hdl,'FaceAlpha',1,'LineStyle','none')
set(gca,'Color',[0 0 0]), colorbar
set(gca,'CLim',[-5,-2]), view(-7,16)
set(gca,'XTick',0:100,'YTick',0:.5:1,'ZTick',0:.5:1)
title(['Amplitude, n = ' num2str(m)])

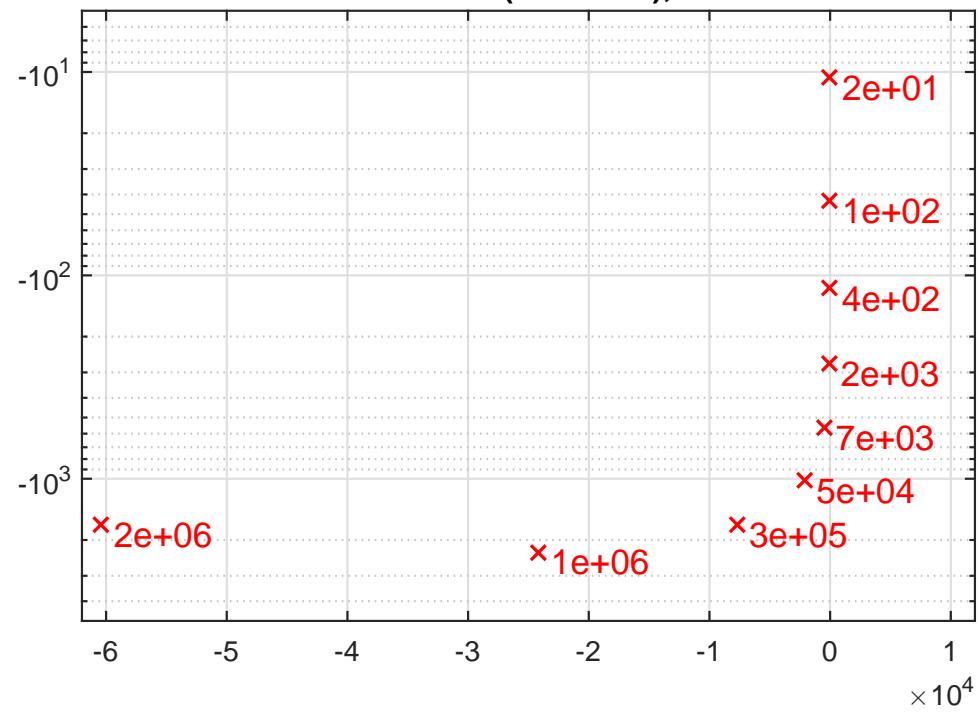
figure
Ang = angle(Vol); Ang(Ang<0) = 2*pi+Ang(Ang<0);
hdl = slice(x,y,z,Ang,xslice,yslice,zslice);
set(hdl,'FaceAlpha',1,'LineStyle','none')
set(gca,'Color',[0 0 0]), set(gca,'CLim',[0,2*pi])
colorbar, view(-7,16)
set(gca,'XTick',0:100,'YTick',0:.5:1,'ZTick',0:.5:1)
title(['Phase, n = ' num2str(m)])
end
end % for m

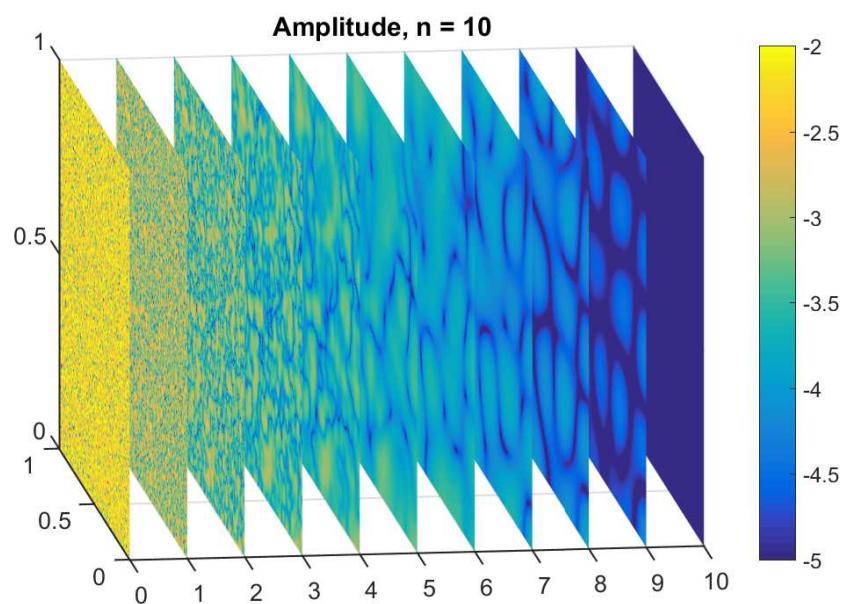
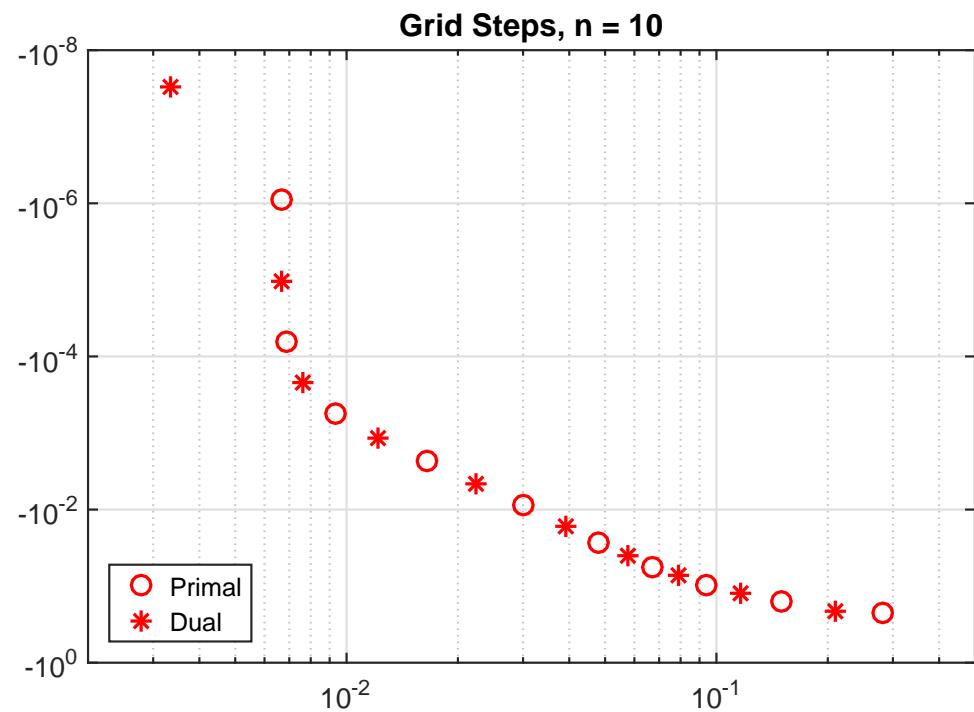
```

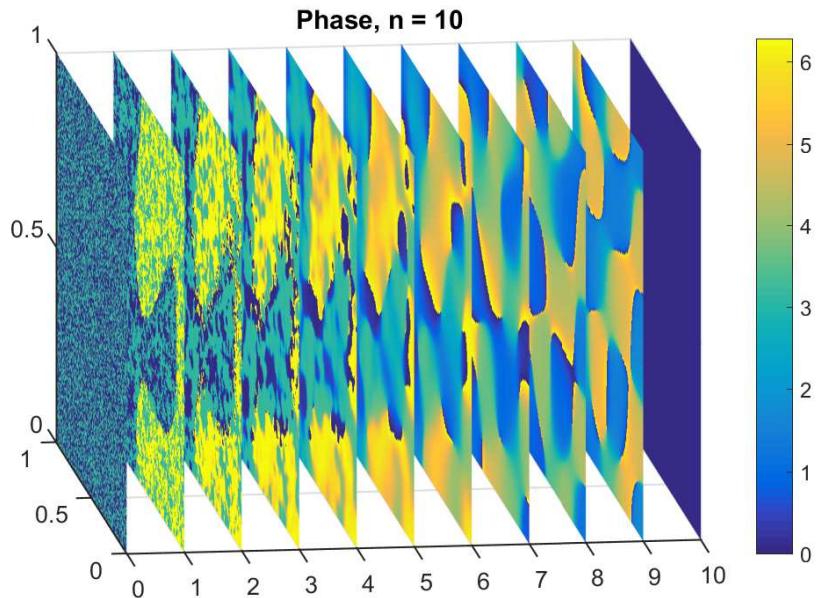
Error Curves, $n = 10$



Poles and Abs(Residues), $n = 10$



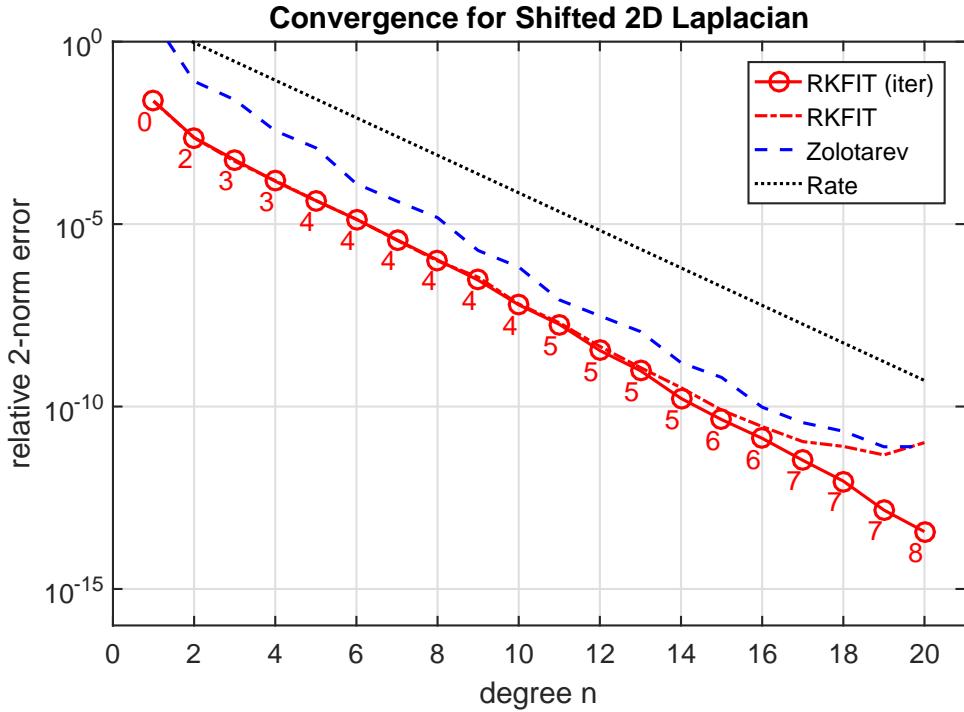




```

figure
semilogy(err_rkfitt,'r-o'), hold on
semilogy(err_rkfit,'r-.')
semilogy(err_zolo,'b--')
rate = exp(-2*pi^2/log((256*a1*b2/a2/b1)));
semilogy(10*rate.^(1:m),'k:')
ylim([1e-16,1]), xlim([0,m+1])
xlabel('degree n')
ylabel('relative 2-norm error')
legend('RKFIT (iter)', 'RKFIT', 'Zolotarev', 'Rate')
labels = num2str(iter_rkfit(:), '%d');
hdl = text((1:m)-.4,err_rkfitt/10,labels,'horizontal','left',...
    'vertical','bottom');
set(hdl,'FontSize',13,'Color','r'), grid on
title('Convergence for Shifted 2D Laplacian')

```



3 Conclusions

The main observation is that for this 2D problem the RKFIT approximants perform very similar to the uniform Zolotarev approximants. Compared to the 1D Laplacian example, no significant superlinear convergence effects are observed. Still the number of required RKFIT iterations is very small.

4 Other examples

The other examples in [2] can be reproduced with the following scripts:

Figure 1.2 - an infinite waveguide with two layers

Example 6.1 - constant coefficient and 1D indefinite Laplacian

Example 6.3 - uniform approximation on indefinite interval

Example 7.1 - truly variable-coefficient case with 2D indefinite Laplacian

5 References

- [1] V. Druskin, S. Güttel, and L. Knizhnerman. *Near-optimal perfectly matched layers for indefinite Helmholtz problems*, SIAM Rev., 58(1):90–116, 2016.
- [2] V. Druskin, S. Güttel, and L. Knizhnerman. *Compressing variable-coefficient exterior Helmholtz problems via RKFIT*, MIMS EPrint 2016.53 (<http://eprints.ma.man.ac.uk/2511/>), Manchester Institute for Mathematical Sciences, The University of Manchester, UK, 2016.